

Autopilot Raymarine



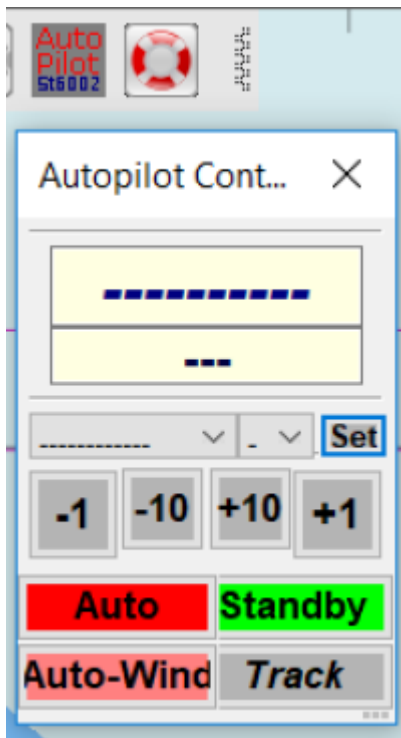
Links

- Source: [Github Source](#)
- Forum: [Autopilot_RM Plugin for Raymarine](#)
- Forum: [Route info to Raymarine via Seataalk](#)
- [Windows Release Download](#)

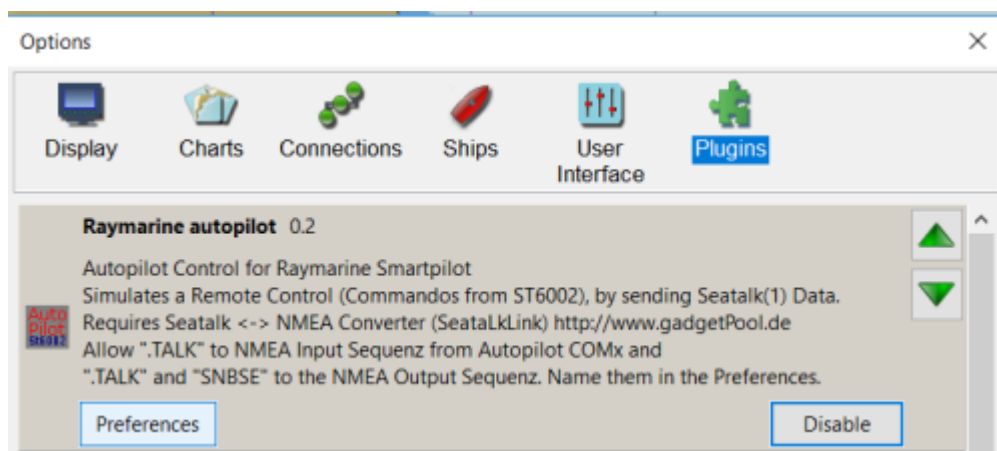
AIM

Provide an OpenCPN Autopilot Control for Raymarine Autopilots. Autopilot can control a Raymarine autopilot by sending and receiving special NMEA messages to the course-computer.

Autopilot-RM Menu



Autopilot-RM Preferences



Documentation

- [ODT Documentation](#)
- [PDF Documentation](#)
- [Docx Documentation](#)

Beta Version

by Bernd Cirotzki

“Autopilot can control a Raymarine autopilot by sending and receiving special NMEA messages to the course-computer.”

“For this functioning it is necessary to convert a messages from “NMEA” to “SEATALK”. For this conversion a special hardware is required. (Seataalk – NMEA converter, Seataalk-link) The hardware can be ordered here : <http://www.gadgetPool.de>

“It is tested with a Raymarine Smartpilot S1G an a ST6002+ Panel. But I think it would work with others too.”

From:
<https://opencpn.org/wiki/dokuwiki/> - **OpenCPN Manuals**

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https://opencpn.org/wiki/dokuwiki/doku.php?id=opencpn:developer_manual:plugins:beta_plugins:autopilot_rm_pi

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